





Introduction

- In this topic, we will
 - Review Taylor series as seen from calculus
 - Introduce a variation on the formula appropriate for this course
 - Look at the error term
 - Observe that the formula tells us exactly how much the error drops
 - Introduce big-O notation to describe the error





The derivative

There are different ways of representing the derivative:

$$f'(x), f''(x), f'''(x)$$

$$\dot{u}(t), \ddot{u}(t), \ddot{u}(t)$$

$$\frac{d}{dx} f(x), \frac{d^2}{dx^2} f(x), \frac{d^3}{dx^3} f(x)$$

— In this course, we will use a variation of the first:

$$f^{(1)}(x), f^{(2)}(x), f^{(3)}(x),...$$

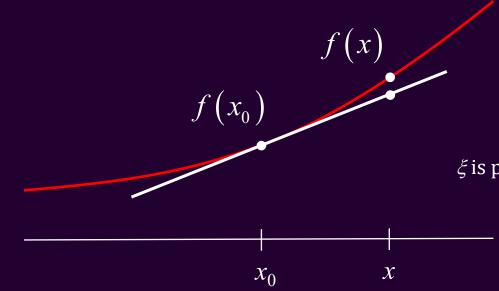




 Given a function where the second derivative is continuous, we know that

$$f(x) \approx f(x_0) + f^{(1)}(x_0)(x - x_0) + \frac{1}{2} f^{(2)}(\xi_0)(x - x_0)^2$$

 $x_0 \le \xi_0 \le x$



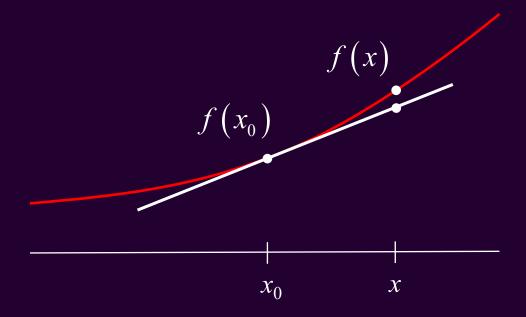
 ξ is pronounced *k-sigh* or *k-see*





• A quick aid-memoire for $x - x_0$ versus $x_0 - x$:

$$f(x) = f(x_0) + f^{(1)}(x_0)(x - x_0) + \frac{1}{2}f^{(2)}(\xi_0)(x - x_0)^2$$







- Mathematicians are generally interested in general solutions:
 - This equation is true for all values of x

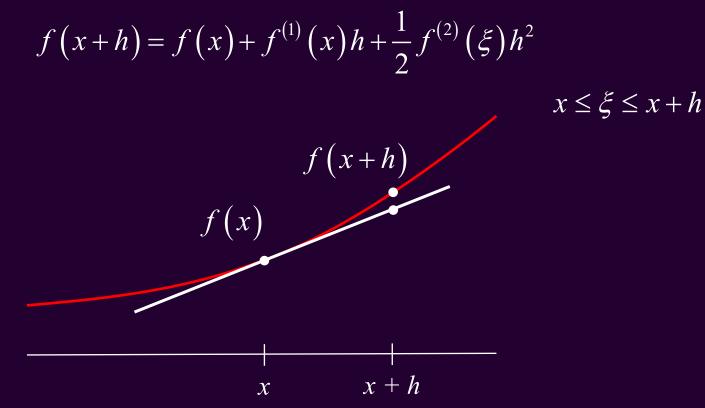
$$f(x) = f(x_0) + f^{(1)}(x_0)(x - x_0) + \frac{1}{2}f^{(2)}(\xi_0)(x - x_0)^2$$

- Engineers, however, are generally only interested in points close to the known value x
 - Thus, instead of having two different values of x and x_0 , we will focus on a point x and approximate the value at x + h





• Thus, our approach will be as follows:







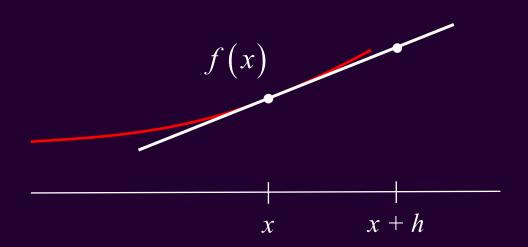
- Thus, we have
 - The exact value
 - The approximation
 - The error

$$f(x+h) = f(x) + f^{(1)}(x)h + \frac{1}{2}f^{(2)}(\xi)h^2$$





- Note that the Taylor series is not useful if the function is not sufficiently differentiable:
 - Flipping a switch in an electrical circuit
 - An object in motion striking another f(x+h)







- Taylor series will generally be used to estimate the error of other techniques we will use
 - The error will be in terms of the absolute error, not relative

$$\frac{1}{2} \left| f^{(2)}(\xi) \right| \left| h \right|^2$$

- When we begin find approximations to solutions to initialvalue problems,
 - Taylor series will be the basis of our formulas





• On occasion, we will use higher order Taylor series

$$f(x+h) = f(x) + f^{(1)}(x)h + \frac{1}{2}f^{(2)}(x)h^2 + \frac{1}{3!}f^{(3)}(\xi)h^3$$
$$f(x+h) = f(x) + f^{(1)}(x)h + \frac{1}{2}f^{(2)}(x)h^2 + \frac{1}{3!}f^{(3)}(x)h^3 + \frac{1}{4!}f^{(4)}(\xi)h^4$$

 The unknown for the error term will always be the Greek equivalent of the variable we are dealing with

$$x$$
 and ξ
 t and τ

 τ is pronounced *tau*, rhyming with *cow*

- To keep life simple, we will use
 - f for functions of x
 - -y for functions of t





Big Oh

You will recall that the error was

$$f(x+h) = f(x) + f^{(1)}(x)h + \frac{1}{2}f^{(2)}(\xi)h^2$$

- Assuming that the second derivative is approximately constant, the only way to make the error smaller is to reduce h
- Thus, if we divide h by two,
 the error should go down by a factor of approximately four
- Also, if we multiply h by two,
 the error should go up by a factor of approximately four





Big Oh

• Suppose we want to approximate $\sin(2 + h)$

n	$h=2^{-n}$	$\sin(2+h)$	Approximation	Absolute $\frac{1}{2}$ error	$\left \sin(2)\right h^2$	Ratio
1	0.5	0.5984721441	0.7012240086	0.1028	0.1137	
2	0.25	0.7780731969	0.8052607177	0.02719	0.02842	0.2646
3	0.125	0.8503197898	0.8572790723	0.006959	0.007104	0.2560
4	0.00625	0.8815297858	0.8832882495	0.001758	0.001776	0.2527
5	0.003125	0.8958509980	0.8962928382	0.0004418	0.0004440	0.2513
6	0.0015625	0.9026844011	0.9027951325	0.0001107	0.0001110	0.2506
7	0.00078125	0.9060185633	0.9060462797	0.00002772	0.00002775	0.2503
8	0.000390625	0.9076649200	0.9076718532	0.000006933	0.000006937	0.2502
9	0.0001953125	0.9084829062	0.9084846400	0.000001734	0.000001734	0.2501
10	0.00009765625	0.9088905999	0.9088910334	0.0000004335	0.0000004336	0.2500





Big Oh

• Consequently, we will describe the error of a first-order Taylor series approximation as $O(h^2)$

$$f(x+h) = f(x) + f^{(1)}(x)h + \frac{1}{2}f^{(2)}(\xi)h^2$$

- Throughout this course, we will find different algorithms to approximate solutions to numerical problems
- In many cases, there will be a parameter h that we can adjust, and the error will depend on that parameter
 - We will see algorithms that are O(h), $O(h^2)$, $O(h^5)$, etc.





Summary

- Following this topic, you now
 - Are aware of Taylor series with respect to f(x + h)
 - Understand the part that Taylor series will play in this course
 - Know that the Taylor formula gives the absolute error
 - If the appropriate derivative is continuous,
 we have a good estimate as to what the error is
 - We have also seen that the 1st-order Taylor series approximation is what we will describe as $O(h^2)$





References

[1] https://en.wikipedia.org/wiki/Taylor_series





Acknowledgments

None so far.





Colophon

These slides were prepared using the Cambria typeface. Mathematical equations use Times New Roman, and source code is presented using Consolas. Mathematical equations are prepared in MathType by Design Science, Inc. Examples may be formulated and checked using Maple by Maplesoft, Inc.

The photographs of flowers and a monarch butter appearing on the title slide and accenting the top of each other slide were taken at the Royal Botanical Gardens in October of 2017 by Douglas Wilhelm Harder. Please see

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